

Why are quadratic normal volatility models analytically tractable?*

Peter Carr[†]

Travis Fisher[‡]

Johannes Ruf[§]

March 15, 2013

Abstract

We discuss the class of “Quadratic Normal Volatility” (QNV) models, which have drawn much attention in the financial industry due to their analytic tractability and flexibility. We characterize these models as those that can be obtained from stopped Brownian motion by a simple transformation and a change of measure that depends only on the terminal value of the stopped Brownian motion. This explains the existence of explicit analytic formulas for option prices within QNV models in the academic literature. Furthermore, via a different transformation, we connect a certain class of QNV models to the dynamics of geometric Brownian motion and discuss changes of numéraires if the numéraire is modelled as a QNV process.

Keywords: Local volatility, Pricing, Foreign Exchange, Riccati equation, Change of numéraire, Local martingale, Semistatic hedging, Hyperinflation

AMS Subject Classification: 60H99, 60G99, 91G20, 91G99

1 Introduction and model

Quadratic Normal Volatility (QNV) models have recently drawn much attention in both industry and academia since they are not only easily tractable as generalizations of the standard Black–Scholes framework but also can be well calibrated to various market scenarios due to their flexibility. In this paper, we focus on associating the dynamics of QNV processes with the dynamics of Brownian motion and geometric Brownian motion. These relationships reveal why analytic formulas for option prices can be (and indeed have been) found. However, we shall abstain here from computing explicit option prices implied by a QNV model. Formulas for these can be found, for example, in Andersen (2011).

*We thank Alex Lipton and Nicolas Perkowski for their helpful comments on an early version of this paper. We are grateful to the two anonymous referees and the associate editor for their careful reading and very helpful suggestions, which improved this paper. The views represented herein are the authors’ own views and do not necessarily represent the views of Morgan Stanley or its affiliates and are not a product of Morgan Stanley research.

[†]New York University, Courant Institute, E-mail: pcarr@nyc.rr.com

[‡]E-mail: traviswfisher@gmail.com

[§]University of Oxford, Oxford-Man Institute of Quantitative Finance and Mathematical Institute, E-mail: johannes.ruf@oxford-man.ox.ac.uk

It is well known that, in complete strict local martingale models, interpreting expectations as prices leads to seemingly paradoxical contingent claim prices. For example, standard put-call parity is not satisfied in such models, as Andersen (2011) discusses. However, as we illustrate in our companion paper, Carr et al. (2013), a simple adjustment to standard prices yields a pricing rule that bypasses those issues and, moreover, leads to prices that can be interpreted, in some sense, as minimal hedging costs. With these considerations in mind, the reader should not worry about the fact that, under certain parameter constellations, a QNV process is not a true martingale, but a strict local martingale. Instead, the reader should keep in mind that one always can use sums of certain expectations as (adjusted) prices and thus avoid all those issues related to the pricing of contingent claims with strict local martingales as underlying. In Section 6 of this paper, we provide formulas to compute these prices for arbitrary path-dependent contingent claims.

After introducing QNV models in this section and providing an overview of the relevant literature, we show in Section 2 how QNV models can be obtained from transforming a stopped Brownian motion. In Section 3, we work out a connection between a certain class of QNV processes and geometric Brownian motion, and, in Section 4, we formalize the observation that QNV models are stable under changes of numéraires. Section 5 contains some preliminary results on semistatic hedging within QNV models, and Section 6 provides an interpretation of the strict local martingale dynamics of certain QNV processes as the possibility of a hyperinflation under a dominating measure, in the spirit of Carr et al. (2013). The appendix contains a technical result.

Model

If not specified otherwise, we work on a filtered probability space $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, \mathbb{Q})$, equipped with a Brownian motion $B = \{B_t\}_{t \geq 0}$. We introduce a process $Y = \{Y_t\}_{t \geq 0}$ with deterministic initial value $Y_0 = y_0 > 0$, whose dynamics solve

$$dY_t = (e_1 Y_t^2 + e_2 Y_t + e_3) dB_t, \quad (1)$$

where $e_1, e_2, e_3 \in \mathbb{R}$. Problem 3.3.2 in McKean (1969) yields the existence of a unique, strong solution to this stochastic differential equation. We define S as the first hitting time of zero by Y and shall also study a stopped version $X = \{X_t\}_{t \geq 0}$ of Y , defined by $X_t := Y_t^S := Y_{t \wedge S}$ for all $t \geq 0$. We set $x_0 := X_0 = y_0$.

The dynamics of Y and X of course strongly depend on the parameters e_1, e_2, e_3 in the quadratic polynomial $P(z) := e_1 z^2 + e_2 z + e_3$ appearing in (1). We shall say that Y (X) is a (stopped) QNV process¹ with polynomial P . The most important special cases are the following:

- $e_1 = e_2 = 0$, corresponding to Brownian motion;
- $e_1 = e_3 = 0$, corresponding to geometric Brownian motion;
- $e_2 = e_3 = 0$, corresponding to the reciprocal of a three-dimensional Bessel process.

Feller's test for explosions directly yields that Y does not hit any real roots of P (except if $P(y_0) = 0$, in which case $Y \equiv y_0$ would just be constant); see Theorem 5.5.29 in Karatzas and

¹We use the word "normal" in the name Quadratic Normal Volatility to emphasize the fact that we are interested in a model where the normal local volatility is quadratic, as opposed to the lognormal local volatility, such as in the specification $(d\tilde{Y}_t)/\tilde{Y}_t = (e_1 \tilde{Y}_t^2 + e_2 \tilde{Y}_t + e_3) dB_t$.

Shreve (1991). The \mathbb{Q} -local martingales Y and X are not necessarily true \mathbb{Q} -martingales. Indeed, the configuration of the roots of P determines whether Y and X are true \mathbb{Q} -martingales or strict \mathbb{Q} -local martingales:

Proposition 1 (Martingality of QNV processes). *The cases where the QNV process Y is a true martingale are exactly the case when $e_1 = 0$ and the case when P has two real roots $r_1, r_2 \in \mathbb{R}$ with $r_1 \leq r_2$ and $y_0 \in [r_1, r_2]$. The cases where the stopped QNV process X is a true martingale are exactly the case when $e_1 = 0$ and the case when P has a root $r \in \mathbb{R}$ with $x_0 \leq r$.*

The proposition is proved in Section 4.

Relevant literature

An incomplete list of authors who study QNV models in various degrees of generality consists of the following:

- Rady and Sandmann (1994), Rady (1997), Miltersen et al. (1997), Goldys (1997), Ingersoll (1997), and Lipton (2001), who study the case when X is bounded and thus a true martingale in the context of foreign exchange and interest rate markets; related is the class of rational lognormal models introduced by Flesaker and Hughston (see ??);
- Albanese et al. (2001) and Lipton (2002), who derive prices for European calls on X in the case when P has one or two real roots;
- Zühlsdorff (2001, 2002), Andersen (2011), and Chibane (2011), who compute prices for European calls and puts in the general case.

Most of these papers focus on deriving analytic expressions for the pricing of European-style contingent claims. We refer the reader to Andersen (2011) for the precise formulas of European call and put prices. In the following sections, we shall derive purely probabilistic methods to easily compute the price of any, possibly path-dependent, contingent claim.

2 Connection to Wiener process

Bluman (1980, 1983), Carr et al. (2002), and Lipton (2001) prove that the partial differential equations (PDEs) corresponding to the class of QNV models are the only parabolic PDEs that can be reduced to the heat equation, via a certain set of transformations. In this section, we derive a probabilistic equivalent while, in particular, paying attention to the issues of strict local martingality. More precisely, we shall see that if one starts on a Wiener space equipped with a Brownian motion $W = \{W_t\}_{t \geq 0}$, and one is allowed

1. to stop W at a stopping time τ , yielding $W^\tau = \{W_t^\tau\}_{t \geq 0} := \{W_{t \wedge \tau}\}_{t \geq 0}$,
2. to transform W^τ by a strictly increasing smooth function f , and
3. to change the probability measure with a density process $Z = \{Z_t\}_{t \geq 0}$ of the form $Z_t = \tilde{g}(t, W_t^\tau)$ for all $t \geq 0$ for some nonnegative measurable function \tilde{g} ,

then $\{f(W_t^\tau)\}_{t \geq 0}$ is, under the new measure, a QNV process up to time τ , given that it is a local martingale.

Our proof of Theorem 1, which shows this characterization of QNV processes, relies on the characterization of the solutions of three ordinary differential equations (ODEs). The next lemma relates the solutions of these ODEs to each other:

Lemma 1 (Three ODEs). *Fix $C, \mu_0, d, f_0 \in \mathbb{R}$ and $a, b \in [-\infty, \infty]$ with $a < 0 < b$ and let $\mu : (a, b) \rightarrow \mathbb{R}$ solve the ODE*

$$\mu'(x) - \mu(x)^2 = C, \quad \mu(0) = \mu_0. \quad (2)$$

Then the functions $f, g : (a, b) \rightarrow \mathbb{R}$, defined by

$$\begin{aligned} f(x) &:= d \int_0^x \exp\left(2 \int_0^y \mu(z) dz\right) dy + f_0, \\ g(x) &:= \exp\left(-\int_0^x \mu(z) dz\right), \end{aligned} \quad (3)$$

solve the ODEs

$$f'(x) = e_1 f(x)^2 + e_2 f(x) + e_3, \quad f(0) = f_0, \quad (4)$$

$$-g''(x) = Cg(x), \quad g(0) = 1, \quad g'(0) = -\mu_0, \quad (5)$$

respectively, for appropriate $e_1, e_2, e_3 \in \mathbb{R}$.

Proof. The ODE in (5) can be checked easily. To show (4), first consider the case $\mu_0^2 = -C$. The uniqueness of solutions to (2) yields that $\mu \equiv \mu_0$; see, for example, Section 8.2 in Hirsch and Smale (1974). If $\mu_0 \neq 0$, then $f(x) = d(\exp(2\mu_0 x) - 1)/(2\mu_0) + f_0$, and if $\mu_0 = 0$, then $f(x) = dx + f_0$ both satisfy (4). Consider now the case $\mu_0^2 \neq -C$ and observe that then $\mu(x)^2 \neq -C$ for all $x \in (a, b)$, again by a similar uniqueness argument. We obtain that

$$\log\left(\frac{\mu'(x)}{\mu_0^2 + C}\right) = \log\left(\frac{\mu(x)^2 + C}{\mu_0^2 + C}\right) = \int_0^x \frac{2\mu(z)\mu'(z)}{\mu(z)^2 + C} dz = 2 \int_0^x \mu(z) dz.$$

Therefore, $f(x) = d(\mu(x) - \mu_0)/(\mu_0^2 + C) + f_0$, which satisfies (4). \square

The next lemma provides the full set of solutions for the ODEs in (4) and (5):

Lemma 2 (Solutions of ODEs). *Fix $e_1, e_2, e_3, f_0 \in \mathbb{R}$ and set $\mu_0 = e_1 f_0 + e_2/2$, $C = e_1 e_3 - e_2^2/4$, $r_1 = (-e_2/2 - \sqrt{|C|})/e_1$, and $r_2 = (-e_2/2 + \sqrt{|C|})/e_1$. Then the ODE in (4) has a unique solution f , which is defined in a neighborhood (a, b) around zero, with $a, b \in [-\infty, \infty]$ and $a < 0 < b$, such that*

- $\lim_{x \downarrow a} |f(x)| = \infty$ if $a > -\infty$,
- $\lim_{x \uparrow b} |f(x)| = \infty$ if $b < \infty$,
- $f'(x) \neq 0$ for all $x \in (a, b)$, and

- f is infinitely differentiable in (a, b) .

Furthermore, the function $\mu : (a, b) \rightarrow \mathbb{R}$, defined by

$$\mu(x) := \frac{1}{2} \frac{f''(x)}{f'(x)} = e_1 f(x) + \frac{e_2}{2}, \quad (6)$$

satisfies (2). The function $g : (a, b) \rightarrow \mathbb{R}$, defined as in (3), satisfies $\lim_{x \downarrow a} g(x) = 0$ if $a > -\infty$ and $\lim_{x \uparrow b} g(x) = 0$ if $b < \infty$; thus, its domain can be extended to $[a, b] \cap \mathbb{R}$. In explicit form, the functions g and f are as follows:

- if $e_1 = 0$:

$$g(x) = \exp\left(-\frac{e_2 x}{2}\right),$$

$$f(x) = \left(f_0 + \frac{e_3}{e_2}\right) \exp(e_2 x) - \frac{e_3}{e_2} \quad (\text{if } e_2 \neq 0) \quad \text{or} \quad f(x) = e_3 x + f_0 \quad (\text{if } e_2 = 0);$$

- if $C = 0$ and $e_1 \neq 0$:²

$$g(x) = 1 - \mu_0 x = 1 - \left(e_1 f_0 + \frac{e_2}{2}\right) x,$$

$$f(x) = (f_0 - r_1) \frac{1}{1 - \mu_0 x} + r_1 = \left(f_0 + \frac{e_2}{2e_1}\right) \frac{1}{1 - (e_1 f_0 + \frac{e_2}{2}) x} - \frac{e_2}{2e_1};$$

- if $C < 0$ and $e_1 \neq 0$:³

– and, additionally, $f_0 \in (r_1 \wedge r_2, r_1 \vee r_2)$:⁴

$$g(x) = \frac{\cosh(\sqrt{-C}x + c)}{\cosh(c)} = \frac{\cosh\left(\sqrt{\frac{e_2^2}{4} - e_1 e_3} x + c\right)}{\cosh(c)},$$

$$f(x) = \frac{-\sqrt{-C}}{e_1} \tanh(\sqrt{-C}x + c) - \frac{e_2}{2e_1}$$

$$= \frac{-\sqrt{\frac{e_2^2}{4} - e_1 e_3}}{e_1} \tanh\left(\sqrt{\frac{e_2^2}{4} - e_1 e_3} x + c\right) - \frac{e_2}{2e_1}$$

with

$$c := \operatorname{arctanh}\left(\frac{-\mu_0}{\sqrt{-C}}\right) = \frac{1}{2} \log\left(\frac{\sqrt{-C} - \mu_0}{\sqrt{-C} + \mu_0}\right);$$

²This condition is equivalent to the condition that the polynomial P , defined by $P(z) = e_1 z^2 + e_2 z + e_3$, has a double root $r \in \mathbb{R}$. The quadratic formula then yields that $r = r_1 = r_2$.

³This condition is equivalent to the condition that the polynomial P , defined as above, has two real roots, which are exactly at r_1, r_2 , by the quadratic formula.

⁴This condition is equivalent to $\mu_0 \in (-\sqrt{-C}, \sqrt{-C})$.

– and, additionally, $f_0 \notin [r_1 \wedge r_2, r_1 \vee r_2]$.⁵

$$g(x) = \frac{\sinh(\sqrt{-C}x + c)}{\sinh(c)} = \frac{\sinh\left(\sqrt{\frac{e_2^2}{4} - e_1 e_3}x + c\right)}{\sinh(c)},$$

$$f(x) = \frac{-\sqrt{-C}}{e_1} \coth(\sqrt{-C}x + c) - \frac{e_2}{2e_1}$$

$$= \frac{-\sqrt{\frac{e_2^2}{4} - e_1 e_3}}{e_1} \coth\left(\sqrt{\frac{e_2^2}{4} - e_1 e_3}x + c\right) - \frac{e_2}{2e_1}$$

with

$$c := \operatorname{arccoth}\left(\frac{-\mu_0}{\sqrt{-C}}\right) = \frac{1}{2} \log\left(\frac{-\sqrt{-C} + \mu_0}{\sqrt{-C} + \mu_0}\right);$$

– and, additionally, $f_0 \in \{r_1 \wedge r_2, r_1 \vee r_2\}$.⁶

$$g(x) = \exp(-\mu_0 x),$$

$$f(x) \equiv f_0;$$

• if $C > 0$:⁷

$$g(x) = \frac{\cos(\sqrt{C}x + c)}{\cos(c)} = \frac{\cos\left(\sqrt{e_1 e_3 - \frac{e_2^2}{4}}x + c\right)}{\cos(c)},$$

$$f(x) = \frac{\sqrt{C}}{e_1} \tan(\sqrt{C}x + c) - \frac{e_2}{2e_1} = \frac{\sqrt{e_1 e_3 - \frac{e_2^2}{4}}}{e_1} \tan\left(\sqrt{e_1 e_3 - \frac{e_2^2}{4}}x + c\right) - \frac{e_2}{2e_1}$$

with $c := \arctan(\mu_0/\sqrt{C})$.

Proof. The existence and uniqueness of solutions of the ODE in (4) follow from standard arguments in the theory of ODEs; see Section 8.2 in Hirsch and Smale (1974). The fact that μ satisfies the corresponding ODE and the other statements can be checked easily. \square

The description of the solutions of the ODEs in (4) and (5) is the fundamental step in proving the following theorem, which characterizes QNV processes as the only local martingales that can be simulated from stopped Brownian motion by a certain set of transformations:

Theorem 1 (QNV process and Brownian motion). *Let $\Omega = C([0, \infty), \mathbb{R})$ be the set of continuous paths $\omega : [0, \infty) \rightarrow \mathbb{R}$. Let $\mathbb{F} = \{\mathcal{F}_t\}_{t \geq 0}$ denote the filtration generated by the canonical process W , defined by $W_t(\omega) := \omega(t)$ for all $t \geq 0$, and set $\mathcal{F} = \bigvee_{t \geq 0} \mathcal{F}_t$. Let \mathbb{P} denote the Wiener measure on (Ω, \mathcal{F}) . Then the following statements hold:*

⁵This condition is equivalent to $\mu_0 \notin [-\sqrt{-C}, \sqrt{-C}]$.

⁶This condition is equivalent to $\mu_0 \in \{-\sqrt{-C}, \sqrt{-C}\}$.

⁷This condition is equivalent to the condition that the polynomial P , defined as above, has no real roots.

1. Fix $a, b \in [-\infty, \infty]$ with $a < 0 < b$ and let $f : [a, b] \rightarrow [-\infty, \infty]$ and $\tilde{g} : [0, \infty) \times [a, b] \rightarrow [0, \infty)$ denote two measurable functions with $\tilde{g}(0, 0) = 1$, $\lim_{x \downarrow a} |f(x)| = \infty = |f(a)|$ if $a > -\infty$, and $\lim_{x \uparrow b} |f(x)| = \infty = |f(b)|$ if $b < \infty$. Assume that f is three times continuously differentiable in (a, b) and that $f'(x) \neq 0$ for all $x \in (a, b)$. Define the \mathbb{F} -stopping time τ by

$$\tau := \inf\{t \geq 0 | W_t \notin (a, b)\}, \quad \inf \emptyset := \infty, \quad (7)$$

and the processes $Y = \{Y_t\}_{t \geq 0}$ and $Z = \{Z_t\}_{t \geq 0}$ by $Y_t := f(W_t^\tau)$ and $Z_t := \tilde{g}(t, W_t^\tau)$ for all $t \geq 0$. Assume that Z is a (nonnegative) \mathbb{P} -martingale and that Y is a \mathbb{Q} -local martingale, where \mathbb{Q} denotes the unique probability measure on $(\Omega, \bigvee_{t \geq 0} \mathcal{F}_t)$ satisfying $d\mathbb{Q}/d\mathbb{P}|_{\mathcal{F}_t} = Z_t$ for all $t \geq 0$.⁸

Then Y under \mathbb{Q} satisfies

$$dY_t = (e_1 Y_t^2 + e_2 Y_t + e_3) dB_t \quad (8)$$

for all $t \geq 0$ and for some $e_1, e_2, e_3 \in \mathbb{R}$ and a \mathbb{Q} -Brownian motion $B = \{B_t\}_{t \geq 0}$; to wit, Y is a \mathbb{Q} -QNV process. Furthermore, the corresponding density process Z is of the form $Z_t = \exp(C(t \wedge \tau)/2)g(W_t^\tau) = \exp(Ct/2)g(W_t^\tau)$ for all $t \geq 0$, where g is explicitly computed in Lemma 2 (with the corresponding constants e_1, e_2, e_3 and $f_0 = f(0)$) and $C = e_1 e_3 - e_2^2/4$.

2. Conversely, for any $e_1, e_2, e_3, f_0 \in \mathbb{R}$ there exist $a, b \in [-\infty, \infty]$ with $a < 0 < b$ and measurable functions $f : [a, b] \cap \mathbb{R} \rightarrow [-\infty, \infty]$ and $g : [a, b] \cap \mathbb{R} \rightarrow [0, \infty)$ such that the following hold:

- f is infinitely differentiable in (a, b) , $f'(x) \neq 0$ for all $x \in (a, b)$, $\lim_{x \downarrow a} |f(x)| = \infty$ if $a > -\infty$, and $\lim_{x \uparrow b} |f(x)| = \infty$ if $b < \infty$;
- the process $Z = \{Z_t\}_{t \geq 0}$, defined by $Z_t = \exp(Ct/2)g(W_t^\tau)$ for all $t \geq 0$ with $C = e_1 e_3 - e_2^2/4$ and τ as in (7), is a \mathbb{P} -martingale and generates a probability measure \mathbb{Q} on $(\Omega, \bigvee_{t \geq 0} \mathcal{F}_t)$;
- the process $Y = \{Y_t\}_{t \geq 0}$, defined by $Y_t = f(W_t^\tau)$ for all $t \geq 0$, has under \mathbb{Q} the dynamics in (8), for some \mathbb{Q} -Brownian motion $B = \{B_t\}_{t \geq 0}$, and satisfies $Y_0 = f_0$.

Proof. We start with the proof of the first statement. Observe that zero is an absorbing point of the martingale Z since it is also a nonnegative supermartingale. Thus, by the martingale representation theorem (see, for example, Theorem III.4.33 of Jacod and Shiryaev, 2003), there exists some progressively measurable process $\tilde{\mu} = \{\tilde{\mu}_t\}_{t \geq 0}$ such that the dynamics of Z can be described as $dZ_t = -Z_t \tilde{\mu}_t dW_t$ for all $t \geq 0$. Then Lenglart's extension of Girsanov's theorem implies that the process $B = \{B_t\}_{t \geq 0}$, defined by $B_t := W_t + \int_0^t \tilde{\mu}_s ds$ for all $t \geq 0$, is a \mathbb{Q} -Brownian motion; see Theorem VIII.1.12 in Revuz and Yor (1999).

Itô's formula yields that

$$dY_t = df(W_t) = f'(W_t)dW_t + \frac{1}{2}f''(W_t)dt = f'(W_t)dB_t + \left(\frac{1}{2}f''(W_t) - f'(W_t)\tilde{\mu}_t\right)dt \quad (9)$$

⁸See page 192 in Karatzas and Shreve (1991).

for all $t < \tau$. Now, the uniqueness of the Doob–Meyer decomposition (see Theorem III.16 in Protter, 2003), in conjunction with (9) and the fact that Y is a \mathbb{Q} -local martingale, implies that $\tilde{\mu}_t = \mu(W_t)$ for all $t < \tau$, where we have defined

$$\mu(x) := \frac{1}{2} \frac{f''(x)}{f'(x)}$$

for all $x \in (a, b)$. By the assumption on f , the function μ is continuously differentiable in (a, b) .

Then another application of Itô's formula yields that

$$\log(\tilde{g}(t, W_t)) = - \int_0^t \mu(W_s) dW_s - \frac{1}{2} \int_0^t \mu(W_s)^2 ds = -\eta(W_t) + \frac{1}{2} \int_0^t (\mu'(W_s) - \mu(W_s)^2) ds \quad (10)$$

for all $t < \tau$, where $\eta : (a, b) \rightarrow (-\infty, \infty)$ is defined as $\eta(x) = \int_0^x \mu(y) dy$ for all $x \in (a, b)$. Then Lemma 5 in Appendix A yields that μ satisfies the ODE of (2) in (a, b) for some $C \in \mathbb{R}$. Lemma 1 implies that f solves the ODE of (4); in conjunction with (9), this yields (8). Lemma 2 yields that $C = e_1 e_3 - e_2^2/4$. The expression for \tilde{g} in (10) implies that Z is of the claimed form, first for all $t < \tau$ and then for $t = \tau$ since $Z_\tau = 0$ if $\tau < \infty$ because $\mathbb{Q}(Y_t \in \mathbb{R} \text{ for all } t \geq 0) = 1$.

For the converse direction, fix e_1, e_2, e_3, f_0 and apply Lemma 2. Define Z as in the statement with the corresponding function g , computed in Lemma 2. Assume for a moment that the corresponding change of measure exists, that is, Z is a \mathbb{P} -martingale. The computations in (9) then imply that Y is a \mathbb{Q} -local martingale with dynamics as in (8), where \mathbb{Q} is as in the statement.

Thus, it remains to show that Z is a \mathbb{P} -martingale. This is clear in the cases $e_1 = 0$ and $C \geq 0$ since Z then is either a stopped \mathbb{P} -(geometric) Brownian motion or a bounded \mathbb{P} -martingale by Itô's formula. We conclude by writing Z as the sum of two true martingales, in the case $C < 0$, using $\sinh(x) := (\exp(x) - \exp(-x))/2$ and $\cosh(x) := (\exp(x) + \exp(-x))/2$. \square

The next corollary concludes this discussion by illustrating how expectations of path-dependent functionals in QNV models can be computed. Here and in the following, we shall always assume $\infty \cdot \mathbf{1}_A(\omega) = 0$ if $\omega \notin A$ for any $A \in \mathcal{F}$, for the sake of notation.

Corollary 1 (Computation of expectations in QNV models). *Fix $T > 0$, $y_0 > 0$, $e_1, e_2, e_3 \in \mathbb{R}$, and $C = e_1 e_3 - e_2^2/4$ and let $h : C([0, T], \mathbb{R}) \rightarrow [0, \infty]$ denote any nonnegative measurable function of continuous paths. Let Y (X) denote a (stopped) QNV process with polynomial $P(z) = e_1 z^2 + e_2 z + e_3$ and $Y_0 = y_0$ ($= X_0$) and $W = \{W_t\}_{t \geq 0}$ a Brownian motion.*

Then there exist functions f, g and a stopping time τ (adapted to the filtration generated by W) such that

$$\begin{aligned} \mathbb{E}[h(\{Y_t\}_{t \in [0, T]})] &= \mathbb{E} \left[h(\{f(W_t^T)\}_{t \in [0, T]}) \mathbf{1}_{\{\tau > T\}} \exp\left(\frac{CT}{2}\right) g(W_T^T) \right], \\ \mathbb{E}[h(\{X_t\}_{t \in [0, T]})] &= \mathbb{E} \left[h(\{f(W_t^{\tau \wedge S})\}_{t \in [0, T]}) \mathbf{1}_{\{\tau > T \wedge S\}} \exp\left(\frac{C(T \wedge S)}{2}\right) g(W_T^{\tau \wedge S}) \right], \end{aligned}$$

where S denotes the first hitting time of zero by the process $\{f(W_t)\}_{t \geq 0}$.

Proof. The statement follows directly from Theorem 1, first for bounded h and then for any non-negative h , by taking the limit after observing that, in the notation of Theorem 1, $\{\tau > T\} = \{g(W_T^T) > 0\}$. \square

With the notation of the last corollary and Lemma 2, let us define $\underline{W}_T := \min_{t \in [0, T]} W_t$ and $\overline{W}_T := \max_{t \in [0, T]} W_t$. Then the event $E_1 := \{\tau > T\}$ can be represented as $\{a < \underline{W}_T < \overline{W}_T < b\}$. Without loss of generality assuming $\mu_0 \geq 0$, we have the following:

- $E_1 = \Omega$ if $e_1 = 0$ or both $C < 0$ and $\mu_0 \in [-\sqrt{-C}, \sqrt{-C}]$;
- $E_1 = \{\overline{W}_T < 1/\mu_0\}$ if $e_1 \neq 0$ and $C = 0$;
- $E_1 = \{\overline{W}_T < -c/\sqrt{-C}\}$ if $e_1 \neq 0$ and $C < 0$ and $\mu_0 \notin [-\sqrt{-C}, \sqrt{-C}]$;
- $E_1 = \{(c - \pi/2)/\sqrt{C} < \underline{W}_T < \overline{W}_T \leq (c + \pi/2)/\sqrt{C}\}$ if $C > 0$.

The event $E_2 := \{\tau > T \wedge S\}$ has the same representation with W always replaced by W^S . It can easily be checked that $E_2 = \Omega$ if the polynomial corresponding to the stopped QNV process X has a root greater than x_0 . These considerations illustrate that for any QNV model, quantities of the form $\mathbb{E}[\tilde{h}(Y_T)]$ or $\mathbb{E}[\tilde{h}(X_T)]$ can easily be computed by using only the joint distribution of Brownian motion together with its running minimum and maximum.

For later use, we state the following simple observation:

Lemma 3 (Reciprocal of a solution f). *Fix $e_1, e_2, e_3, f_0 \in \mathbb{R}$ with $f_0 \neq 0$. For the solution $f : (a, b) \rightarrow \mathbb{R}$ of (4), with $a, b \in [-\infty, \infty]$ denoting possible times of explosion of f , consider μ and g , as in (6) and (3). Define $\hat{a} = \sup\{x \in (a, 0] | f(x) = 0\} \vee a$ and $\hat{b} = \inf\{x \in [0, b] | f(x) = 0\} \wedge b$ and consider the functions $\hat{f}, \hat{\mu}, \hat{g} : (\hat{a}, \hat{b}) \rightarrow \mathbb{R}$, defined by $\hat{f}(x) := 1/f(x)$, $\hat{\mu}(x) := \hat{f}''(x)/(2\hat{f}'(x))$, and $\hat{g}(x) := \exp(-\int_0^x \hat{\mu}(z) dz)$.*

Then \hat{f} solves the Riccati equation

$$\hat{f}'(x) = -e_3 \hat{f}(x)^2 - e_2 \hat{f}(x) - e_1, \quad \hat{f}(0) = f_0^{-1}, \quad (11)$$

and \hat{g} satisfies $\hat{g} = g f / f_0$. In particular, if $\hat{a} > -\infty$ (resp., $\hat{b} < \infty$), then $\lim_{x \downarrow \hat{a}} g(x) f(x)$ (resp., $\lim_{x \uparrow \hat{b}} g(x) f(x)$) exists and is real.

Proof. Observe that $\hat{f}'(x) = -f'(x)/f(x)^2$, which directly yields (11). Now, the identity $\hat{\mu} = \mu - f'/f$ implies that

$$\hat{g}(x) = \exp\left(-\int_0^x \hat{\mu}(z) dz\right) = g(x) \exp\left(\int_0^x \frac{f'(z)}{f(z)} dz\right) = \frac{g(x)f(x)}{f_0}.$$

The existence of the limits follows as in Lemma 2. □

3 Connection to geometric Brownian motion

We now focus on the case when Y is a QNV process with a polynomial P that has exactly two real roots r_1, r_2 . For that, we parameterize P as $P(z) = e_1(z - r_1)(z - r_2)$ for some $e_1 \in \mathbb{R} \setminus \{0\}$ and $r_1, r_2 \in \mathbb{R}$ with $r_1 < r_2$.

In the following, we shall connect the dynamics of a QNV process to geometric Brownian motion. This link has been established for the case $y_0 \in (r_1, r_2)$ in Rady (1997).

Theorem 2 (QNV process and geometric Brownian motion). Fix $T > 0$, $e_1, r_1, r_2, y_0 \in \mathbb{R}$ with $e_1 \neq 0$ and $r_1 < r_2$ and let $h : C([0, T], \mathbb{R}) \rightarrow [0, \infty]$ denote any nonnegative measurable function of continuous paths. Let $Y = \{Y_t\}_{t \geq 0}$ denote a QNV process with polynomial $P(z) = e_1(z - r_1)(z - r_2)$ and $Y_0 = y_0$, and $Z = \{Z_t\}_{t \geq 0}$ a (possibly negative) geometric Brownian motion with $Z_0 = (y_0 - r_2)/(y_0 - r_1)$ and

$$\frac{dZ_t}{Z_t} = e_1(r_2 - r_1)dB_t \quad (12)$$

for all $t \geq 0$, where $B = \{B_t\}_{t \geq 0}$ denotes some Brownian motion. Let τ denote the first hitting time of 1 by Z . Then we have that

$$\mathbb{E}[h(\{Y_t\}_{t \in [0, T]})] = \frac{y_0 - r_1}{r_2 - r_1} \mathbb{E} \left[h \left(\left\{ \frac{r_2 - r_1 Z_t}{1 - Z_t} \right\}_{t \in [0, T]} \right) \mathbf{1}_{\{\tau > T\}} (1 - Z_T) \right]. \quad (13)$$

Proof. Define two processes $M = \{M_t\}_{t \geq 0}$ and $N = \{N_t\}_{t \geq 0}$ by

$$M_t := \frac{y_0 - r_1}{r_2 - r_1} \cdot (1 - Z_t) \mathbf{1}_{\{\tau > t\}} \quad \text{and} \quad N_t := \frac{r_2 - r_1 Z_t}{1 - Z_t} \cdot \mathbf{1}_{\{\tau > t\}}$$

for all $t \geq 0$. Then M is a nonnegative martingale, started in one, and thus defines a new probability measure $\tilde{\mathbb{Q}}$ by $d\tilde{\mathbb{Q}} = M_T d\mathbb{Q}$. Moreover, the right-hand side of (13) can be written as

$$\mathbb{E} [h(\{N_t\}_{t \in [0, T]}) \mathbf{1}_{\{\tau > T\}} M_T] = \mathbb{E}^{\tilde{\mathbb{Q}}} [h(\{N_t\}_{t \in [0, T]})]$$

since $\tilde{\mathbb{Q}}(\tau > T) = 1$. Therefore, and because of $N_0 = y_0$, it is sufficient to show that N is a $\tilde{\mathbb{Q}}$ -QNV process with polynomial P . Observe that, under $\tilde{\mathbb{Q}}$, Itô's formula yields that

$$d\langle N \rangle_t = \left(\frac{r_2 - r_1}{(1 - Z_t)^2} \right)^2 d\langle Z \rangle_t = e_1^2 \frac{(r_2 - r_1)^4 Z_t^2}{(1 - Z_t)^4} dt = e_1^2 (N_t - r_1)^2 (N_t - r_2)^2 dt = P(N_t)^2 dt.$$

Thus, provided that N is a continuous $\tilde{\mathbb{Q}}$ -local martingale on $[0, T]$, the one-dimensional version of Theorem 3.4.2 in Karatzas and Shreve (1991) (in conjunction with the weak uniqueness of solutions to the underlying stochastic differential equation) yields that N is a QNV process with polynomial P under $\tilde{\mathbb{Q}}$.

It remains to be shown that N is a $\tilde{\mathbb{Q}}$ -local martingale on $[0, T]$. Towards this end, since $\tilde{\mathbb{Q}}(\tau > T) = 1$, it is sufficient to show that N^{τ_i} is a $\tilde{\mathbb{Q}}$ -martingale for all $i \in \mathbb{N}$, where τ_i is defined as the first hitting time of $1/i$ by M . However, this follows from the observation that $N^{\tau_i} M^{\tau_i}$ is a \mathbb{Q} -martingale and from Girsanov's theorem; see also Exercise VIII.1.20 in Revuz and Yor (1999). \square

In the setup of Theorem 2, we observe that the process Z is negative if and only if $y_0 \in (r_1, r_2)$, exactly the case treated by Rady (1997). In that case, $\tau = \infty$ \mathbb{Q} -almost surely as Z never hits 1. It is also exactly this case when Y is a true martingale; compare Proposition 1. Indeed, using $h(\omega) = \omega_T$ in (13) shows that

$$\begin{aligned} \mathbb{E}[Y_T] &= \frac{y_0 - r_1}{r_2 - r_1} \mathbb{E} [(r_2 - r_1 Z_T) \mathbf{1}_{\{\tau > T\}}] = \frac{y_0 - r_1}{r_2 - r_1} (\mathbb{E} [r_2 - r_1 Z_T^\tau] - (r_2 - r_1) \mathbb{Q}(\tau \leq T)) \\ &= y_0 - (y_0 - r_1) \mathbb{Q}(\tau \leq T), \end{aligned}$$

which equals y_0 if and only if $y_0 \in (r_1, r_2)$.

Remark 1 (Brownian motion and three-dimensional Bessel process). With the notation of Theorem 2, set $r_1 = 0$ and $y_0 = e_1 = 1$. Furthermore, let $\widetilde{M} = \{\widetilde{M}_t\}_{t \geq 0}$ denote a Brownian motion starting in one and stopped in zero and let $\widetilde{Y} = \{\widetilde{Y}_t\}_{t \geq 0}$ denote the reciprocal of a three-dimensional Bessel process starting in one; that is, \widetilde{Y} is a QNV process with polynomial $\widetilde{P}(z) = z^2$ and satisfies $\widetilde{Y}_0 = 1$.

Formally, as $r_2 \downarrow 0$, the dynamics of the QNV process Y , described by the polynomial $P(z) = z(z - r_2)$, resemble more and more those of \widetilde{Y} . Similarly, consider the process $M = \{M_t\}_{t \geq 0}$, defined in the proof of Theorem 2 as $M_t = (1 - Z_t^r)/r_2$ for all $t \geq 0$, and observe that

$$M_t = \frac{1 - Z_t^r}{r_2} = \frac{1}{r_2} \left(1 - (1 - r_2) \exp \left(r_2 B_t^r - \frac{r_2^2 t}{2} \right) \right) = 1 - B_t^r + O(r_2)$$

for all $t \geq 0$ by a Taylor series expansion. Thus, as $r_2 \downarrow 0$, in distribution the martingale M resembles, more and more, the Brownian motion \widetilde{M} .

Observe, furthermore, that the process $N = \{N_t\}_{t \geq 0}$, defined in the proof of Theorem 2, satisfies $N_t = 1/M_t$ for all $t \geq 0$. Thus, Theorem 2 states, with the given parameters, that $N = 1/M$ has the same distribution as Y after changing the probability measure with the Radon–Nikodym derivative M_T . Indeed, it is well known that the reciprocal $\widetilde{N} = 1/\widetilde{M}$ has the dynamics of \widetilde{Y} after changing the probability measure with the Radon–Nikodym derivative \widetilde{M}_T ; see also Perkowski and Ruf (2012). Thus, Theorem 2 extends this well-known relationship of Brownian motion and Bessel process to processes that are, in some sense, approximately Brownian motion and Bessel process. \square

4 Closedness under changes of measure

Before studying specific changes of measure involving QNV processes, let us make some general observations. Towards this end, fix a nonnegative continuous local martingale $\widetilde{X} = \{\widetilde{X}_t\}_{t \geq 0}$ with $\widetilde{X}_0 = 1$, defined on a filtered probability space $(\Omega, \bigvee_{t \geq 0} \mathcal{F}_t, \{\mathcal{F}_t\}_{t \geq 0}, \mathbb{P})$. Let $\{\tau_n\}_{n \in \mathbb{N}}$ denote the first hitting times of levels $n \in \mathbb{N}$ by \widetilde{X} and observe that \widetilde{X} defines a sequence of consistent probability measures $\{\widetilde{\mathbb{P}}_n\}_{n \in \mathbb{N}}$ on $\{\mathcal{F}_{\tau_n}\}_{n \in \mathbb{N}}$ via $d\widetilde{\mathbb{P}}_n = (\lim_{t \uparrow \infty} \widetilde{X}_t^{\tau_n}) d\mathbb{P}$. Under sufficient technical assumptions, this sequence of probability measures can be extended to a measure $\widetilde{\mathbb{P}}$ on $\bigvee_{n \in \mathbb{N}} \mathcal{F}_{\tau_n}$; in particular, the probability space must be large enough to allow for an event that has zero probability under \mathbb{P} but positive probability under $\widetilde{\mathbb{P}}$; for details and further references we refer the reader to Subsection 2.2 in Ruf (2013).

We remark that we usually may assume that the necessary technical assumptions hold by embedding \widetilde{X} in a “sufficiently nice” canonical space, as long as we are interested in distributional properties of functionals of the path of X ; see also Remark 1 in Ruf (2013). We shall call $\widetilde{\mathbb{P}}$ the Föllmer measure⁹ corresponding to \widetilde{X} .

⁹Föllmer (1972) realized the usefulness of relating probability measures to nonnegative supermartingales, in particular, to nonnegative local martingales. Meyer (1972), giving credit to H. Föllmer, simplified the construction of these measures, and Delbaen and Schachermayer (1995) used these results to develop an understanding of strict local martingales in the theory of no-arbitrage.

One can prove that

$$\mathbb{E}^{\tilde{\mathbb{P}}} \left[\frac{1}{\tilde{X}_T} \left(H \mathbf{1}_{\{\tilde{X}_T < \infty\}} \right) \right] = \mathbb{E}^{\mathbb{P}} \left[H \mathbf{1}_{\{\tilde{X}_T > 0\}} \right] \quad (14)$$

for all \mathcal{F}_T -measurable random variables $H \in [0, \infty]$ and $T \geq 0$, where we again have set $\infty \cdot \mathbf{1}_A(\omega) = 0$ if $\omega \notin A$ for any $A \in \mathcal{F}_T$. Furthermore, $1/\tilde{X}$ is a $\tilde{\mathbb{P}}$ -local martingale and, moreover, \tilde{X} is a strict $\tilde{\mathbb{P}}$ -local martingale if and only if $\tilde{\mathbb{P}}(\tilde{X}_T = \infty) > 0$ for some $T > 0$. It is important to note that \mathbb{P} and $\tilde{\mathbb{P}}$ are not equivalent if \tilde{X} is a strict \mathbb{P} -local martingale or has positive probability (under \mathbb{P}) to hit zero. See again Ruf (2013) for a proof of these statements.

We now recall the stopped \mathbb{Q} -QNV process X , defined as $X := Y^S$, where S denotes the first hitting time of zero by the \mathbb{Q} -QNV process Y . In particular, X is a nonnegative \mathbb{Q} -local martingale. In order to allow for the not necessarily equivalent change to the Föllmer measure, we shall assume, throughout the following sections, that Ω is the space of nonnegative continuous paths, taking values in $[0, \infty]$ and being absorbed when hitting either zero or infinity, and that X is the canonical process on this space. Moreover, we shall assume that $\mathcal{F} = \bigvee_{n \in \mathbb{N}} \mathcal{F}_{\tau_n}$, where $\{\tau_n\}_{n \in \mathbb{N}}$ again denotes the first hitting times of levels $n \in \mathbb{N}$ by X , and that the Föllmer measure corresponding to X exists; we shall denote it by $\hat{\mathbb{Q}}$.

The change of measure from \mathbb{Q} to $\hat{\mathbb{Q}}$ has the financial interpretation as the change of risk-neutral dynamics if the numéraire changes. For example, if X represents the price of Euros in Dollars and if \mathbb{Q} is a risk-neutral measure for prices denoted in Dollars, then $\hat{\mathbb{Q}}$ corresponds to the measure under which asset prices denoted in Euros (instead of Dollars) follow local martingale dynamics.

Next, we study this change of measure for stopped QNV processes and observe that the class of stopped QNV processes is stable under changes of numéraires, a feature that makes QNV processes attractive as models for foreign exchange rates. We start with a simple observation that is related to the statement of Lemma 3:

Lemma 4 (Roots of quadratic polynomial). *We consider the polynomial $P(z) := e_1 z^2 + e_2 z + e_3$ of Section 1 and its counterpart $\hat{P}(z) := -z^2 P(1/z) = -e_3 z^2 - e_2 z - e_1$. They satisfy the following duality relations:*

- (i) P has only complex roots if and only if \hat{P} has only complex ones;
- (ii) P has two non-zero roots if and only if \hat{P} has only two non-zero roots;
- (iii) P has zero as a single root if and only if $\hat{P}(z)$ is linear and non-constant, and vice versa;
- (iv) P has zero as a double root if and only if \hat{P} is constant, and vice versa.

Proof. The statement follows from simple considerations, such as that if $r \in \mathbb{R} \setminus \{0\}$ is a root of P , then $1/r$ is a root of \hat{P} . \square

In the context of the next proposition, we remind the reader of (11), which we shall utilize in the next section.

Proposition 2 (Closedness under a change of numéraire). *The process $\hat{X} := 1/X$ is a stopped QNV process with polynomial $\hat{P}(z) := -e_3 z^2 - e_2 z - e_1$ under the Föllmer measure $\hat{\mathbb{Q}}$ corresponding to X as underlying. In particular, the following hold:*

- (i) X under \mathbb{Q} is a QNV process with complex roots if and only if \widehat{X} is one under $\widehat{\mathbb{Q}}$;
- (ii) X under \mathbb{Q} is a QNV process with two real non-zero roots if and only if \widehat{X} is one under $\widehat{\mathbb{Q}}$;
- (iii) X under \mathbb{Q} is a QNV process with a single root at zero if and only if \widehat{X} under $\widehat{\mathbb{Q}}$ is a (possibly stopped) shifted geometric Brownian motion;¹⁰
- (iv) X under \mathbb{Q} is a QNV process with a double root at zero if and only if \widehat{X} under $\widehat{\mathbb{Q}}$ is a (constantly time-changed) stopped Brownian motion.

Proof. The reciprocal \widehat{X} of X is a $\widehat{\mathbb{Q}}$ -local martingale by the discussion at the beginning of this section. Let $\{\tau_n\}_{n \in \mathbb{N}}$ again denote the first hitting times of levels $n \in \mathbb{N}$ by X . Then we observe that $\widehat{\mathbb{Q}}$ is absolutely continuous with respect to \mathbb{Q} on \mathcal{F}_{τ_n} for all $n \in \mathbb{N}$. Thus, by Lenglart's extension of Girsanov's theorem (see also Theorem VIII.1.4 in Revuz and Yor, 1999), \widehat{X}^{τ_n} is (up to stopping) a QNV process with polynomial \widehat{P} for all $n \in \mathbb{N}$. Since we assumed that $\bigvee_{n \in \mathbb{N}} \mathcal{F}_{\tau_n} = \mathcal{F}$ and, therefore, $\widehat{\mathbb{Q}}$ is uniquely determined through the π -system $\bigcup_{n \in \mathbb{N}} \mathcal{F}_{\tau_n}$, we can conclude that \widehat{X} is a stopped $\widehat{\mathbb{Q}}$ -QNV process with polynomial \widehat{P} . The statements in (i) to (iv) follow from Lemma 4. \square

We now are ready to give a simple proof of Proposition 1, stated in the introduction:

Proof of Proposition 1. Consider the probability measure $\widehat{\mathbb{Q}}$ and the stopped $\widehat{\mathbb{Q}}$ -QNV process \widehat{X} introduced in Proposition 2. By the discussion at the beginning of this section, strict local martingality of X is equivalent to $\widehat{\mathbb{Q}}(\widehat{X}_T = 0) > 0$ for some $T > 0$. We shall use the fact, discussed in Section 1, that \widehat{X} does not hit any roots of \widehat{P} . Thus, $\widehat{\mathbb{Q}}(\widehat{X}_T = 0) > 0$ for some $T > 0$ is equivalent to the polynomial \widehat{P} not having any nonnegative real roots less than or equal to $1/x_0$. This again is equivalent to $e_1 \neq 0$ together with the condition that P has no roots greater than or equal to x_0 ; this is due to the fact that $e_1 = 0$ implies that 0 is a root of \widehat{P} and that $r \in (0, \infty)$ is a root of P if and only if $1/r$ is a root of \widehat{P} ; see Lemma 4. Thus, we have proven the statement concerning the martingality of X .

If $e_1 = 0$, then Y is either constant or Brownian motion (if $e_2 = 0$) or $\widetilde{Y} := Y + e_3/e_2$ is geometric Brownian motion (if $e_2 \neq 0$). In all these cases, Y is a true martingale. If y_0 lies between two roots of P , then Y is bounded and thus a martingale. For the reverse direction, assume that Y is a martingale and that $e_1 \neq 0$. Then there exists a root $r \geq y_0$ of P since otherwise $X = Y^S$ is a strict local martingale. Denote the second root of P by \widetilde{r} and define the QNV process $\widetilde{Y} := r - Y$ with polynomial $P^{\widetilde{Y}}(z) = -e_1 z(z - (r - \widetilde{r}))$. It is clear that \widetilde{Y} is again a martingale and thus, by the same argument, $r - \widetilde{r} \geq \widetilde{Y}_0 = r - y_0$, which yields the statement. \square

Alternatively, we could have used the criterion in Kotani (2006) to prove Proposition 1.

5 Semistatic hedging

In the following, we present an interesting symmetry that can be applied for the semistatic replication of barrier options in certain parameter setups.

¹⁰We call a QNV process with linear, but not constant, polynomial “shifted geometric Brownian motion.”

Proposition 3 (Symmetry). *We fix $T > 0$ and assume that X is a stopped QNV process with a polynomial of the form $P(z) = ez^2/L + e_2z + eL$ and $x_0 = L$ for some $L > 0$ and $e, e_2 \in \mathbb{R}$. Let $h : [0, \infty] \rightarrow [0, \infty]$ denote some measurable nonnegative function satisfying $h(0) = 0$ and $h(\infty) \in \mathbb{R}$. We then have the equivalence*

$$h\left(\frac{X_T}{L}\right) \in \mathcal{L}^1(\mathbb{Q}) \Leftrightarrow h\left(\frac{L}{X_T}\right) \frac{X_T}{L} \in \mathcal{L}^1(\mathbb{Q}),$$

where $\mathcal{L}(\mathbb{Q})$ denotes the space of integrable random variables with respect to \mathbb{Q} , and the identity

$$\mathbb{E}\left[h\left(\frac{X_T}{L}\right)\right] = \mathbb{E}\left[h\left(\frac{L}{X_T}\right) \frac{X_T}{L}\right]. \quad (15)$$

In particular, by using $h(x) = \mathbf{1}_{x>0}\mathbf{1}_{x<\infty}$, we obtain that

$$\mathbb{E}[X_T] = L\mathbb{Q}(X_T > 0),$$

and by replacing $h(x)$ by $h(x)\mathbf{1}_{x>L}$,

$$\mathbb{E}\left[h\left(\frac{X_T}{L}\right) \mathbf{1}_{\{X_T>L\}}\right] = \mathbb{E}\left[h\left(\frac{L}{X_T}\right) \frac{X_T}{L} \mathbf{1}_{\{X_T<L\}}\right]. \quad (16)$$

Proof. We observe that $Z = \{Z_t\}_{t \geq 0}$, defined by $Z_t := X_t/L$ for all $t \geq 0$, is a stopped QNV process with a polynomial of the form $P(z) = ez^2 + e_2z + e$ and satisfies $Z_0 = 1$. Thus, we can assume, without loss of generality, that $L = 1$. Now, (14), with $H = h(X_T)$, yields, for the Föllmer measure $\widehat{\mathbb{Q}}$ corresponding to X , that

$$\mathbb{E}[h(X_T)] = \mathbb{E}^{\widehat{\mathbb{Q}}}\left[\frac{h(X_T)}{X_T}\right] = \mathbb{E}\left[h\left(\frac{1}{X_T}\right) X_T\right],$$

where the second equality follows from observing that $1/X$ has the same distribution under $\widehat{\mathbb{Q}}$ as X has under \mathbb{Q} ; see Proposition 2. This shows (15), and the other parts of the statement follow from it directly. \square

Remark 2 (Alternative proof of Proposition 3). Proposition 3 can also directly be shown without relying on the Föllmer measure. For this, we again assume $L = 1$ and define the sequences of processes X^n ($X^{1/n}$) by stopping X as soon as it hits n ($1/n$) for all $n \in \mathbb{N}$. We then observe that Girsanov's theorem (Theorem VIII.1.4 of Revuz and Yor, 1999) implies for all $\epsilon > 0$ and all Borel sets $A_\epsilon \subset (\epsilon, \infty)$

$$\mathbb{E}\left[X_T^n \mathbf{1}_{\{1/X_T^n \in A_\epsilon\}}\right] = \mathbb{Q}\left(X_T^{1/n} \in A_\epsilon\right).$$

Now, we first let n go to ∞ and then ϵ to zero and obtain that

$$\mathbb{E}\left[X_T \mathbf{1}_{\{1/X_T \in A\}}\right] = \mathbb{Q}(X_T \in A \cap (0, \infty))$$

for all Borel sets A , which again yields (15). \square

Remark 3 (Semistatic hedging). Proposition 3 and, in particular, (16) can be interpreted as the existence of a semistatic hedging strategy for barrier options in the spirit of Bowie and Carr (1994), Carr et al. (1998), and Carr and Lee (2009).

To see this, consider a QNV process X with a polynomial of the form $P(z) = ez^2/L + e_2z + eL$ and $x_0 > L$ for some $L > 0$ and $e, e_2 \in \mathbb{R}$. Consider further a down-and-in barrier option with barrier L and terminal payoff $h(X_T/L)$ if the barrier is hit by X . For a semistatic hedge, at time zero one buys two positions of European claims, the first paying off $h(X_T/L) \mathbf{1}_{\{X_T \leq L\}}$ and the second paying off $h(L/X_T) X_T/L \mathbf{1}_{\{X_T < L\}}$. If the barrier is not hit, both positions have zero price at time T . If the barrier is hit, however, one sells the second position and buys instead a third position paying off $h(X_T/L) \mathbf{1}_{\{X_T > L\}}$. The equality in (16) guarantees that these two positions have the same price at the hitting time of the barrier. This strategy is semistatic as it requires trading only at maximally two points of time.

Proposition 3, in particular, contains the well-known case of geometric Brownian motion ($e = 0$), where semistatic hedging is always possible. It is an open question to determine more general symmetries than that of Proposition 3. One difficulty arises here from the lack of equivalence of the two measures \mathbb{Q} and $\widehat{\mathbb{Q}}$. However, adding an independent change of time to the dynamics of X preserves any existing such symmetry. \square

6 Joint replication and hyperinflation

In this section, we continue with a financial point of view and interpret the probability measure \mathbb{Q} as the unique risk-neutral measure, under which the stopped QNV process X denotes the price of an asset, say, the price of a Euro in Dollars. The Föllmer measure $\widehat{\mathbb{Q}}$, introduced in Section 4, can then be interpreted as the unique risk-neutral probability measure of a European investor who uses the price of a Euro as a numéraire. To emphasize this point further, we shall use the notation $\mathbb{Q}^\$:= \mathbb{Q}$ and $\mathbb{Q}^\epsilon := \widehat{\mathbb{Q}}$ from now on.

Throughout this section, we assume a finite time horizon $T < \infty$. In the spirit of Carr et al. (2013), we describe a contingent claim by a pair $D = (D^\$, D^\epsilon)$ of random variables such that $D^\$ = H^\$ (\{X_t\}_{t \in [0, T]})$ and $D^\epsilon = H^\epsilon (\{X_t\}_{t \in [0, T]})$ for two measurable functions $H^\$, H^\epsilon : C([0, T], [0, \infty]) \rightarrow [0, \infty]$ satisfying $D^\epsilon = D^\$/X_T$ on the event $\{0 < X_T < \infty\}$. The first component of D represents the claim's (random) payoff denoted in Dollars at time T as seen under the measure $\mathbb{Q}^\$$ and the second its (random) payoff denoted in Euros at time T as seen under the measure \mathbb{Q}^ϵ . In particular, the condition $D^\epsilon = D^\$/X_T$ on the event $\{0 < X_T < \infty\}$ ensures that both the American and the European investors receive the same payoff (in different currencies) in the states of the world that both measures $\mathbb{Q}^\$$ and \mathbb{Q}^ϵ can "see."

We are interested in the quantity

$$p^\$(D) = \mathbb{E}^{\mathbb{Q}^\$} [D^\$] + x_0 \mathbb{E}^{\mathbb{Q}^\epsilon} [D^\epsilon \mathbf{1}_{\{1/X_T=0\}}], \quad (17)$$

derived in Carr et al. (2013). This quantity describes a possible price (in Dollars), the *minimal joint replicating price*, for the claim D . Under additional assumptions on the completeness of the underlying market, this price can be interpreted as the minimal cost of superreplicating the claim's payoffs almost surely under both measures $\mathbb{Q}^\$$ and \mathbb{Q}^ϵ ; observe that these two probability measures are not equivalent if X is a strict local martingale.

Corollary 2 (Minimal joint replicating price in a QNV model). *We have the identity*

$$p^{\$}(D) = \mathbb{E} \left[H^{\$} (\{f(W_t^S)\}_{t \in [0, T]}) \mathbf{1}_{\{\tau > S \wedge T\}} \exp \left(\frac{C(T \wedge S)}{2} \right) g^{\$}(W_T^S) \right] \quad (18)$$

$$+ x_0 \mathbb{E} \left[H^{\epsilon} (\{f(W_t^{\tau})\}_{t \in [0, T]}) \mathbf{1}_{\{\tau \leq S \wedge T\}} \exp \left(\frac{C(T \wedge \tau)}{2} \right) g^{\epsilon}(W_T^{\tau}) \right],$$

where $W = \{W_t\}_{t \geq 0}$ denotes a Brownian motion and S (τ) the first hitting time of zero (infinity) by $\{f(W_t)\}_{t \geq 0}$ and C, f , and $g^{\$} \equiv g$ are as in Corollary 1; moreover, we use g^{ϵ} similarly but corresponding to the stopped QNV process \widehat{X} of Proposition 2.

Proof. By Corollary 1, the first term on the right-hand side of (18) corresponds to $\mathbb{E}^{\mathbb{Q}^{\$}} [D^{\$}]$. Now, Proposition 2 yields that $\widehat{X} = 1/X$ is a stopped \mathbb{Q}^{ϵ} -QNV process for some polynomial \widehat{P} . With the representation \widehat{f} of \widehat{X} (along with \widehat{C} , among others) in Theorem 1 and Corollary 1, Lemma 3 yields that $\widehat{f} = 1/f$, that $\widehat{C} = C$, and that S and τ interchange places. Since $\{\widehat{f}(W_T^{\tau}) = 0\} \cap \{S > \tau \wedge T\} = \{\tau \leq T\} \cap \{\tau \wedge T < S\} = \{\tau \leq S \wedge T\}$, we conclude by applying Corollary 1 to the second term on the right-hand side of (17). \square

We emphasize the symmetry of τ and S , which we relied on in the proof of the corollary. The stopping time τ is the first time $f(W)$ hits infinity and $\widehat{f}(W) = 1/f(W)$ hits zero and the stopping time S satisfies the converse statement.

We also remark that the probability measure \mathbb{P} of Theorem 1 can be interpreted as a physical measure, under which hyperinflations occur with positive probability. Thus, $f(W^S)$ can be used to model an exchange rate that allows (under \mathbb{P}) for hyperinflations in either Euros or Dollars; then $p^{\$}$ represents the minimal replicating cost (in Dollars) for a claim that pays $D^{\$}$ Dollars if no hyperinflation of the Dollar occurs and that pays D^{ϵ} Euros if the Dollar hyperinflates, corresponding to the Dollar price of a Euro being infinity. For a more thorough discussion on this interpretation, we refer the reader to Carr et al. (2013).

Lemma 3 shows that $g^{\epsilon}(W_T^{\tau}) = g^{\$}(W_T^{\tau})f(W_T^{\tau})/x_0$ on $\{\tau \leq S\}$, with multiplications of zero and infinity formally interpreted in such a way as to obtain equality. Moreover, after setting $D^{\epsilon} = \infty$ on $\{S \leq \tau \wedge T\}$ and $D^{\$} = \infty$ on $\{\tau \leq S \wedge T\}$, we also have that $D^{\epsilon} = D^{\$}/f(W_T^{\tau \wedge S})$, again with undefined expressions interpreted in such a way to obtain equality. Therefore, the expression in (18) formally reduces to

$$p^{\$}(D) = \mathbb{E}^{\mathbb{P}} \left[H^{\$} (\{f(W_t^{\tau \wedge S})\}_{t \in [0, T]}) \exp \left(\frac{C(T \wedge S \wedge \tau)}{2} \right) g^{\$}(W_T^{\tau \wedge S}) \right], \quad (19)$$

where all multiplications of 0 with ∞ are interpreted in the sense of (18). Indeed, if all multiplications are well defined, (19) exactly corresponds to (18).

As a brief illustration of the last corollary, consider the minimal joint replicating price of one Euro in Dollars, to wit, $D = (X_T, 1)$. From (18) we obtain that

$$p^{\$}(D) = \mathbb{E} \left[\exp \left(\frac{C(T \wedge S \wedge \tau)}{2} \right) \left((f(W_T^{\tau \wedge S}) \mathbf{1}_{\{\tau > S \wedge T\}}) g^{\$}(W_T^{\tau \wedge S}) + x_0 \mathbf{1}_{\{\tau \leq S \wedge T\}} g^{\epsilon}(W_T^{\tau \wedge S}) \right) \right]$$

$$= x_0 \mathbb{E} \left[\exp \left(\frac{C(T \wedge S \wedge \tau)}{2} \right) \left(\mathbf{1}_{\{\tau > S \wedge T\}} g^{\epsilon}(W_T^{\tau \wedge S}) + \mathbf{1}_{\{\tau \leq S \wedge T\}} g^{\epsilon}(W_T^{\tau \wedge S}) \right) \right]$$

$$= x_0 \mathbb{E} \left[\exp \left(\frac{C(T \wedge S \wedge \tau)}{2} \right) g^\epsilon(W_T^{T \wedge S}) \right] = x_0,$$

where we have used the representation $g^\epsilon = fg^s/x_0$ of Lemma 3. Thus, the minimal replicating cost for one Euro is x_0 Dollars, exactly what we hoped for. We remark that the symbolic representation of (19) directly yields the same statement, too.

A A technical result

The following lemma is used in the proof of Theorem 1:

Lemma 5 (Necessary condition for path independence of integrals). *Let $W = \{W_t\}_{t \geq 0}$ denote a Brownian motion and τ a stopping time of the form (7) for some $a, b \in [-\infty, \infty]$ with $a < 0 < b$. Let $h : (a, b) \rightarrow \mathbb{R}$ denote a continuous function and assume that*

$$\int_0^t h(W_s) ds = \tilde{h}(t, W_t) \quad (20)$$

almost surely on $\{\tau > t\}$ for all $t \geq 0$, for some measurable function $\tilde{h} : [0, \infty) \times (a, b) \rightarrow \mathbb{R}$. Then $h(\cdot) \equiv C$ for some $C \in \mathbb{R}$.

Proof. Assume that (20) holds but h is not a constant. Then there exist some $\epsilon > 0$ and some $y \in (a + \epsilon, b - \epsilon)$ such that $|h(y) - h(0)| = 5\epsilon$; without loss of generality, assume $y \in (0, b - \epsilon)$. Now, define $\tilde{y} := \inf\{y \in [0, b) \mid |h(y) - h(0)| \geq 5\epsilon\}$. Assume, again without loss of generality, that $h(0) = 0$ and $h(\tilde{y}) = 5\epsilon > 0$. Observe that there exists some $\delta \in (0, \min(-a, \epsilon))$ such that $h(y) < \epsilon$ for all y with $|y| < \delta$ and $h(y) \geq 4\epsilon$ for all y with $|y - \tilde{y}| < \delta$. In summary, we assume for the rest of the proof that $h(y) > -5\epsilon$ for all $y \in (-\delta, \tilde{y} + \delta)$, that $h(y) \leq \epsilon$ for all $y \in (-\delta, \delta)$, and that $h(y) \geq 4\epsilon$ for all $y \in (\tilde{y} - \delta, \tilde{y} + \delta)$.

Now, fix $T > 0$ and define

$$\mathfrak{A} := \left\{ \omega \in C([0, T], \mathbb{R}) \mid -\delta < \inf_{s \in [0, T]} \omega_s \leq \sup_{s \in [0, T]} \omega_s < \tilde{y} + \delta, \int_0^T h(\omega_s) ds = \tilde{h}(T, \omega_T) \right\}$$

and $\mathfrak{B} := \{\omega_T : \omega \in \mathfrak{A}\}$. Since h is uniformly continuous on $[-\delta, \tilde{y} + \delta]$, the mapping $\mathfrak{A} \ni \omega \mapsto \int_0^T h(\omega_s) ds = \tilde{h}(T, \omega_T)$ is continuous if \mathfrak{A} is equipped with the supremum norm. Therefore, $\tilde{h}(T, \cdot) : \mathfrak{B} \rightarrow \mathbb{R}$ is continuous and there exists $\tilde{\delta} \in (0, \delta)$ such that $|\tilde{h}(T, y_1) - \tilde{h}(T, y_2)| < \epsilon T$ for all $y_1, y_2 \in (-\tilde{\delta}, \tilde{\delta}) \cap \mathfrak{B}$ since (20) almost surely implies that \mathfrak{B} is dense in $(-\delta, \tilde{y} + \delta)$.

There exists $\omega \in \mathfrak{A}$ such that $-\tilde{\delta} < \inf_{s \in [0, T]} \omega_s \leq \sup_{s \in [0, T]} \omega_s < \tilde{\delta}$ since (20) holds almost surely; thus $\tilde{h}(T, y) < 2\epsilon T$ for all $y \in (-\tilde{\delta}, \tilde{\delta}) \cap \mathfrak{B}$. In order to obtain a contradiction we now consider an $\omega \in \mathfrak{A}$ such that $\omega_T \in (-\tilde{\delta}, \tilde{\delta})$ and $\tilde{h}(T, \omega_T) > 2\epsilon T$. Towards this end, choose an $\omega \in \mathfrak{A}$ such that $\tilde{y} - \delta < \inf_{s \in [0.1T, 0.9T]} \omega_s \leq \sup_{s \in [0.1T, 0.9T]} \omega_s < \tilde{y} + \delta$ and $\omega_T \in (-\tilde{\delta}, \tilde{\delta})$, which again always exists. Observe that for this choice of ω we have $\tilde{h}(T, \omega_T) \geq -0.2T \cdot 5\epsilon + 0.8T \cdot 4\epsilon > 2\epsilon T$. Thus, under the assumptions of the lemma, h is constant. \square

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