

The Complexity of Computing the Solution Obtained by a Specific Algorithm

Paul W. Goldberg

Department of Computer Science
University of Oxford, U. K.

LSE
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It is **PSPACE**-complete to find any Nash equilibria of a game, that are computed by the Lemke-Howson algorithm. ¹

¹(Papadimitriou, G, and Savani '11); “no short cuts”
not every solution is a L-H solution; result also applies to some related
game-solving algorithms

Starting-point

It is **PSPACE**-complete to find any Nash equilibria of a game, that are computed by the Lemke-Howson algorithm. ¹

So, we have taken a specific (exponential-time) algorithm \mathcal{A} for a specific problem (**NASH**), and found out the complexity of computing \mathcal{A} 's solutions...

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A more general class of questions

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LEXMINSAT (find the lexicographically min satisfying assignment) is complete for **OptP** (Krentel '88).

Definition

An **OptP** function f_M has associated poly-time non-det TM M ; M outputs a binary number at each branch of computation; $f_M(x)$ is largest number for all accepting branches.

“easier” than **PSPACE**

Conjecture (attempt to generalize Slide 1)

Given any **PPAD**-complete problem X , and “path-following” algorithm \mathcal{A} for X , it’s **PSPACE**-complete to compute \mathcal{A} ’s output on instances of X .

- **PPAD**?
- “path-following”?

parity argument on a directed graph (Papadimitriou '91):

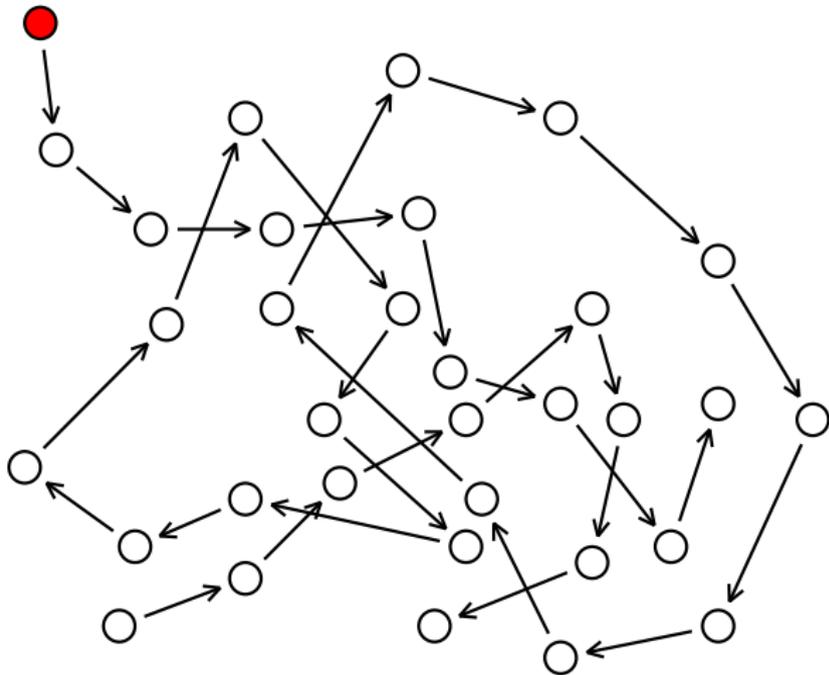
END OF LINE

Given directed graph G of indegree/outdegree at most 1, and a “source” vertex of indegree 0, find another vertex of degree 1. G has vertices $\{0, 1\}^n$ and edges represented by boolean circuits S, P .

END OF LINE characterizes **PPAD**; poly-time reductions between NASH and END OF LINE establish **PPAD**-completeness of NASH².

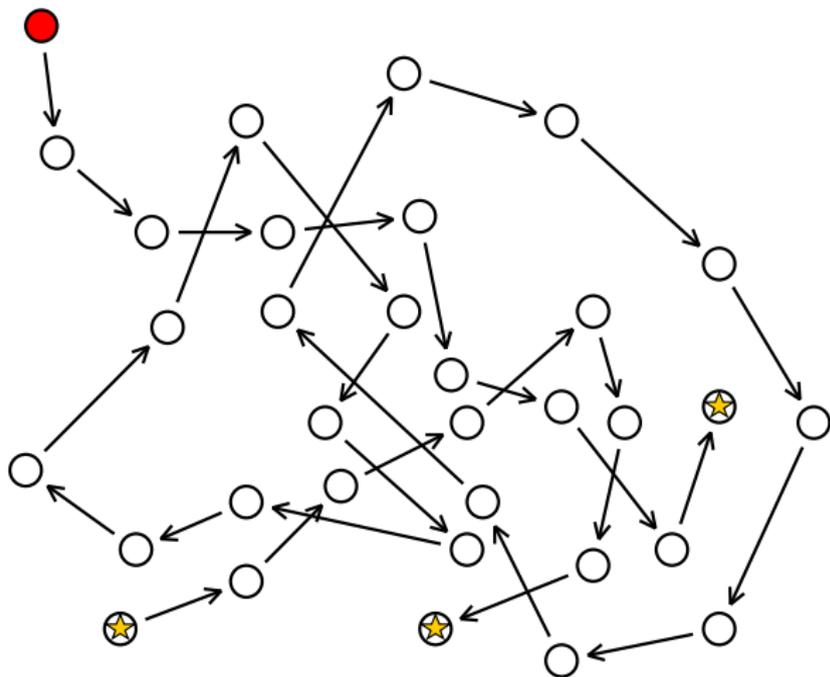
²Daskalakis, G, and Papadimitriou '05,'06; Chen, Deng, and Teng '06

END OF LINE graph



You are given a node with degree 1 (colored red here)

END OF LINE graph



The highlighted nodes are **PPAD**-complete to find.

How hard is **PPAD**?

- “between **P** and **NP**”

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(could there be some other way to prove **PPAD** is as hard as **NP**?)
- anyway, it's assumed not solvable in poly-time, based on effort to find a poly-time algorithm, and usage of general boolean circuits in problem instances

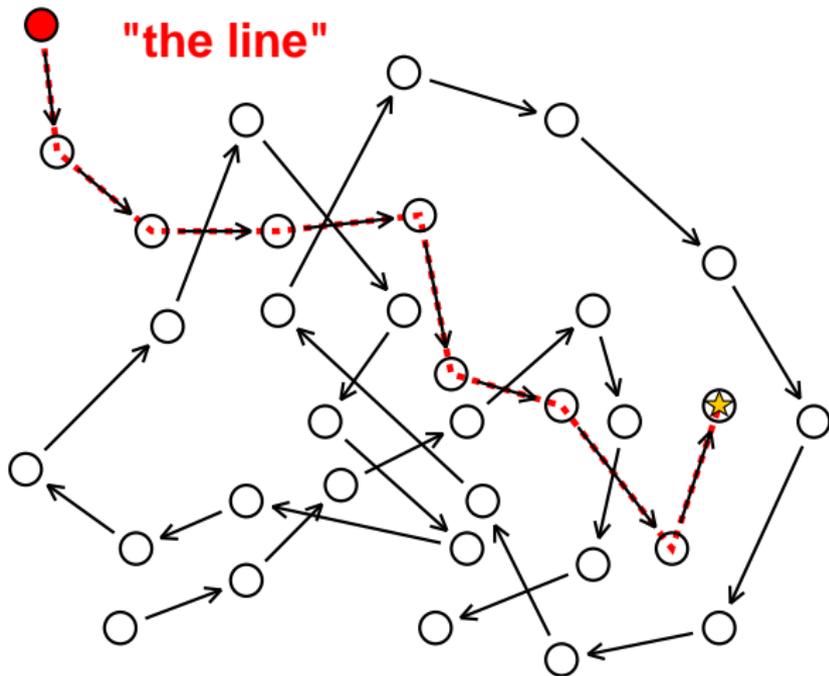
Two “natural” exponential-time algorithms

- lexicographic search
- follow the line

Search for lexicographically-least solution is **OptP**-complete. The search for line-following solution is **PSPACE**-complete!

OTHER END OF THIS LINE (OEOTL) denotes the **PSPACE**-complete search problem.

END OF LINE graph



The node attached to the red node is **PSPACE**-complete to find!

The **PSPACE**-hardness of OEOTL

- The circuits S and P that comprise an instance of END-OF-LINE are like a space-bounded **time-reversible** TM. (nodes of big graph \leftrightarrow configurations)
- It's **PSPACE**-complete to find the config of a space- n TM after 2^n transitions
- TMs can be made time-reversible³ (by remembering some of the previous configs, during a computation)

³Bennett '73,'89; Crescenzi and Papadimitriou '95 (NTMs: depth-bounded tree-like circuit for NTM $\rightarrow (S, P)$ -graph G ; TRUE gates are reachable in G)

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Slide 1: Lemke-Howson serves as a proxy for generic polynomial-space bounded computation.

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Path-following algorithms

definition

A *path-following algorithm* for a **PPAD**-complete problem X uses a reduction to convert X to END OF LINE, follows the line, and uses the same reduction to convert that end-of-line to a solution of X .

Lemke-Howson is path-following, so the result of slide 1 is a special case of the path-following algorithms conjecture.

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Challenge instances for the path-following algorithms conjecture

- $X = \text{NASH}$, $\mathcal{A} = \text{Scarf's algorithm}$
- $X = \text{2D-DISCRETE BROUWER}$, $\mathcal{A} = \text{"the natural algorithm"}$

“Paradox”

PPAD is no harder than **NP** (maybe easier); Lemke-Howson is efficient in practice; *but* it's “harder” to compute the output of Lemke-Howson than the “obviously inefficient” lexicographic search

PPAD easier than NP?

General intuition for the hardness of **PPAD** is that unrestricted boolean circuits are hard to work with...

But note **PPAD** instances have polynomial “query complexity”: consider a computationally unbounded algorithm that wants a solution given the circuits S and P and is able to query their input/output behaviour...

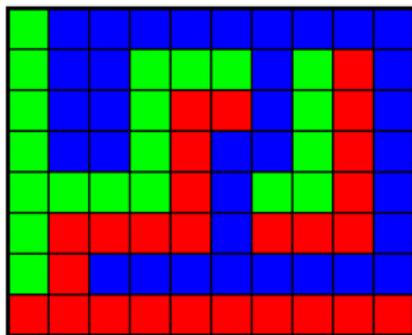
2D-DISCRETE BROUWER

Search for a *panchromatic point* of a *discrete Brouwer function* — in 2D, a function $f : N \times N' \rightarrow \{0, 1, 2\}$ where

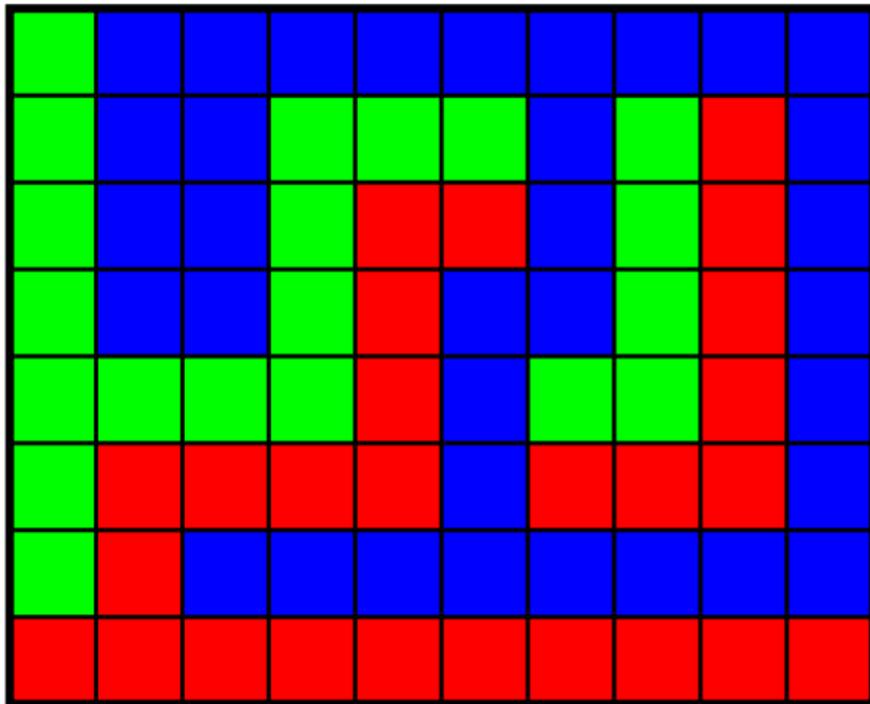
- the bottom row has color 1 (e.g. red)
- the left-hand side has color 2 (e.g. green)
- the top and RHS have color 0 (e.g. blue)
- internal points colored by a poly-size boolean circuit C

Assume N and N' are exponentially large

C maps coordinates to colors

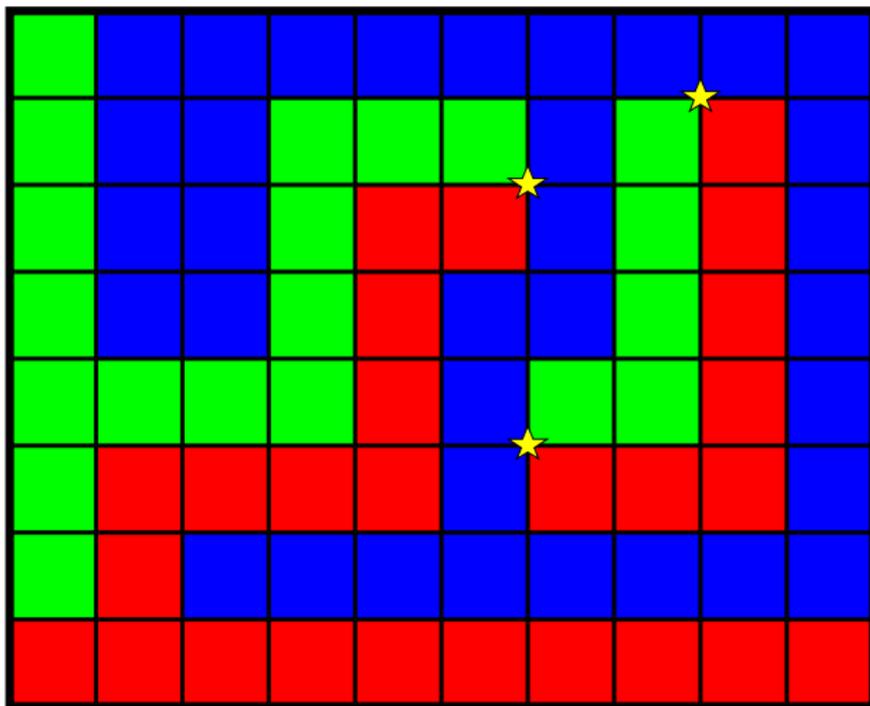


2D-DISCRETE BROUWER example



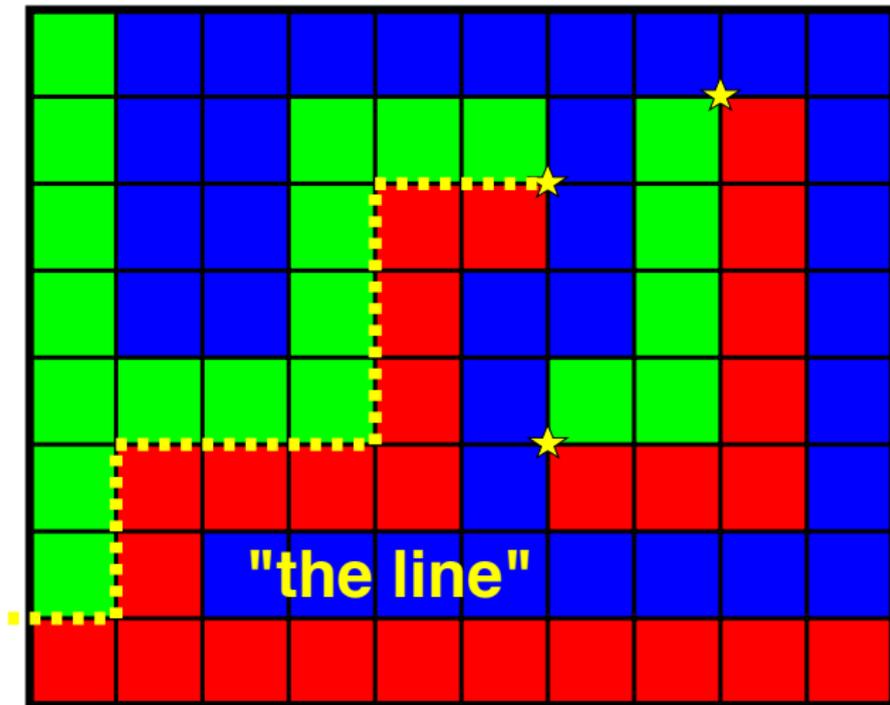
Search for trichromatic point

2D-DISCRETE BROUWER example



Search for trichromatic point... they are **PPAD**-complete to find
(Chen and Deng ('06, '09))

The “natural” path-following algorithm



Follow the line! How hard is it to find this solution?

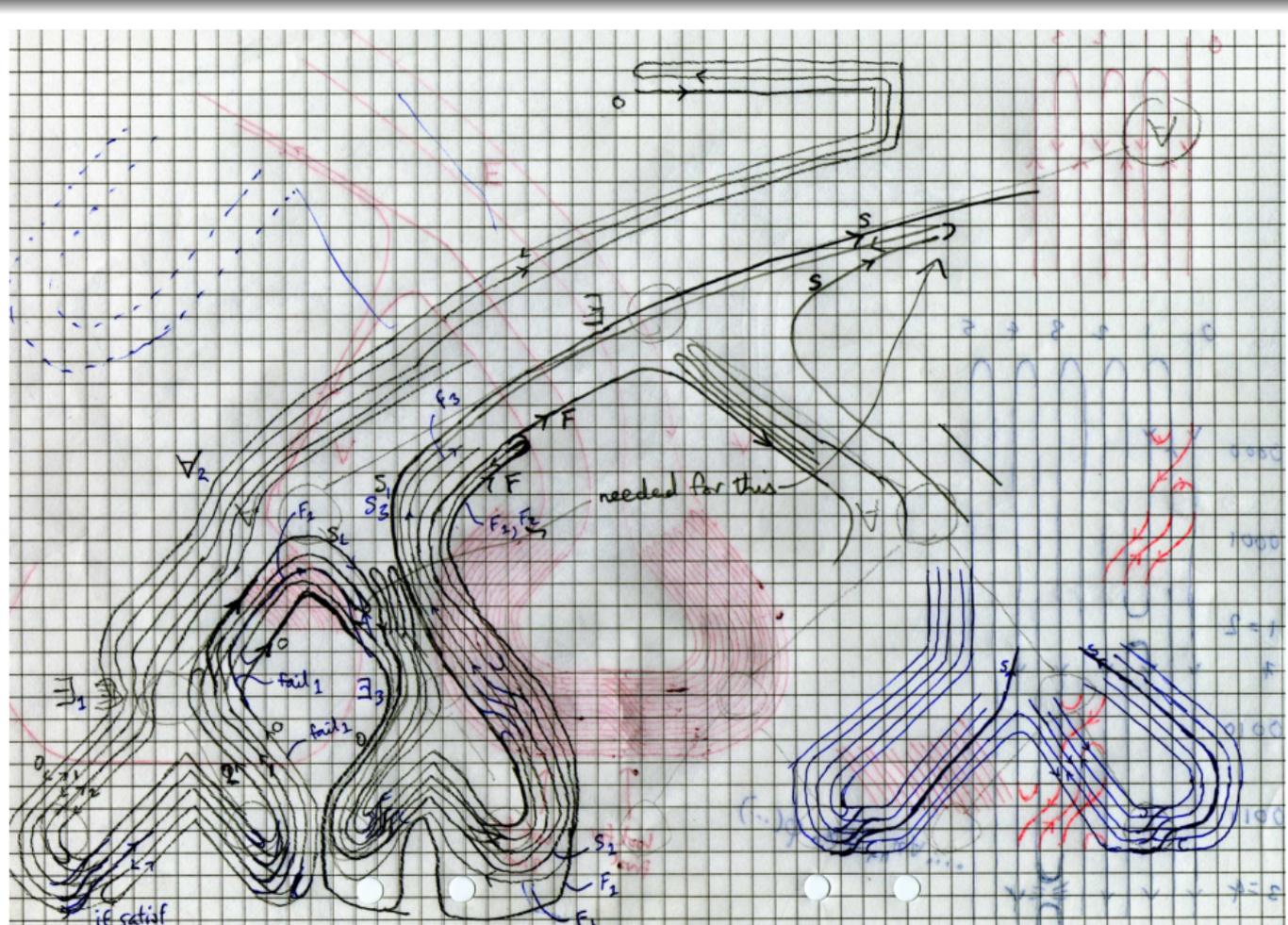
2D DISCRETE BROUWER

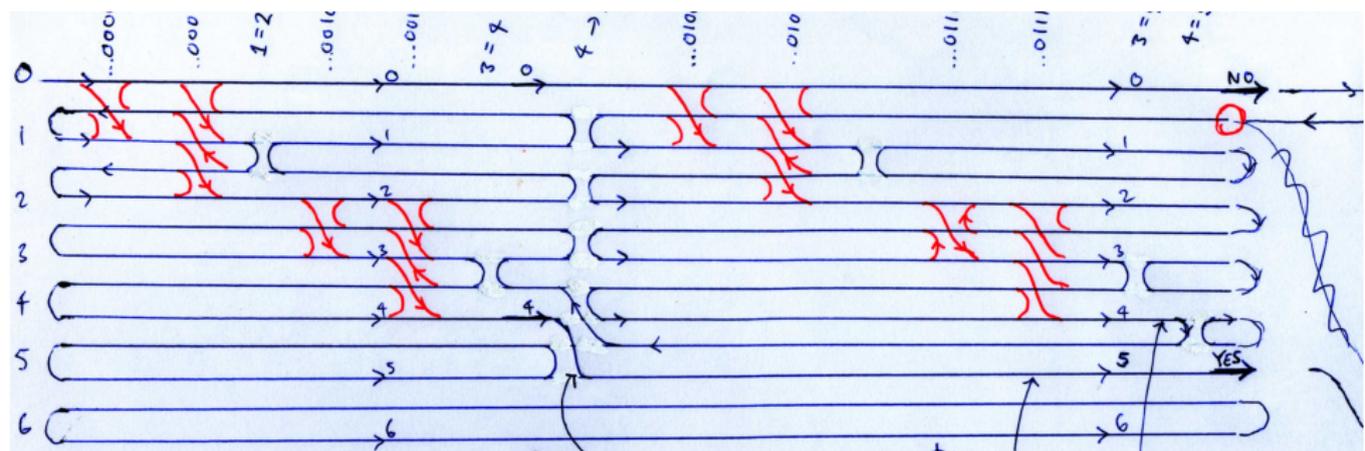
END OF LINE \leq_p 2D-BROUWER (Chen & Deng '06, '09)

theorem

2D-DISCRETE BROUWER is **PSPACE**-complete, if you want the “natural line-following” solution.

The 3D version is easier; 2D needed more work...





at 4 provided
 $\forall x_{n-1} \exists x_n \phi(0..0x_{n-1}x_n)$ satisfied
 else at 0.

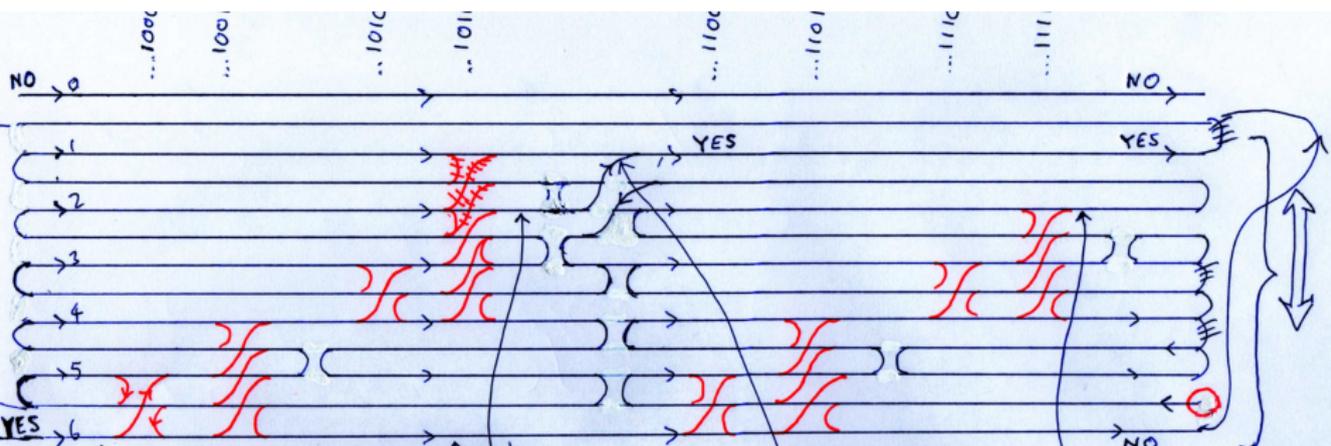
next check: $\forall x_{n-1} \exists x_n \phi(0..0x_{n-1}x_n)$

checked: $\forall x_{n-1} \exists x_n \phi$
 (works for $x_{n-2}=0$)

checked: $\dots \exists x_{n-2} \forall x_{n-1} \exists x_n \phi$
 found it works for $x_{n-2}=1$
 but not $x_{n-2}=0$.

checked above formula,
 found it works for $x_{n-2}=0$
 did not check $x_{n-2}=1$.

$$\dots \exists x_{n-2} \forall x_{n-1} \exists x_n \phi(\dots)$$



$\exists \forall x_n$
 $\forall x_{n-1} = 0; \text{ then } 1$

Continue by checking
 $\dots \forall x_{n-3} \exists x_{n-2} \forall x_{n-1} \exists x_n \phi(0 \dots 0, x_{n-3}, \dots, x_n)$

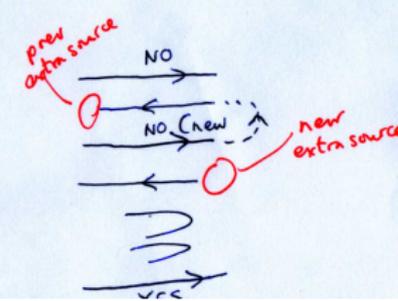
If we reached "NO", ans should be NO.
 connect path-gadgets to YES-wire.

checked $\forall x_{n-3} \exists x_{n-2} \forall x_{n-1} \exists x_n$
 done for $x_{n-3} = 0$ (prev page)
 for $x_{n-3} = 1$ we have done it,
 since it works for $x_{n-2} = 0$

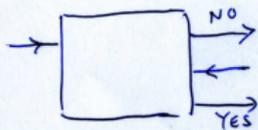
For $x_{n-3} = 0$ we failed, but
 we have another attempt with
 $x_{n-3} = 1$.

shift the successful result
 up 1.

we know we want
 a YES at this
 point.

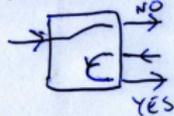


subformulas corresp.
to some variables fixed

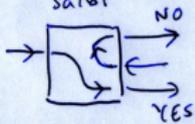


single-variable x_i (all other fixed)

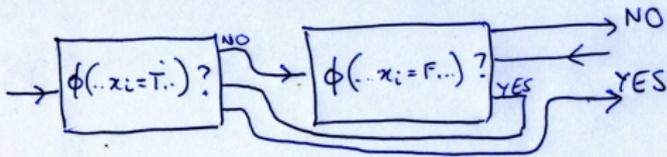
non-satisf



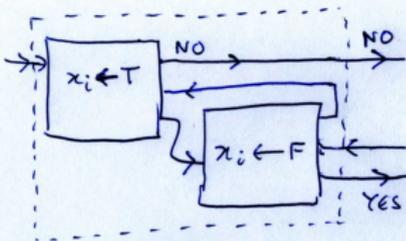
satisf



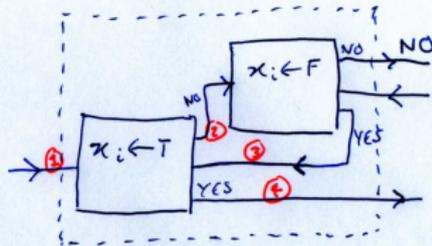
$\exists x_i \phi(\dots)$ (other vars fixed)



$\forall x_i$



$\exists x_i$



At point ③ I will exit at ④.
This is because ① connects to ②,
& there are no loose ends in the
 $x_i \leftarrow T$ circuit.

challenge instance (refined) for path-following conjecture

instances of 2D-DISCRETE BROUWER
generated by specific reductions from END
OF LINE

